

## Important User Information

Solid state equipment has operational characteristics differing from those of electromechanical equipment. Safety Guidelines for the Application, Installation and Maintenance of Solid State Controls (publication [SGI-1.1](#) available from your local Rockwell Automation sales office or online at <http://www.rockwellautomation.com/literature/>) describes some important differences between solid state equipment and hard-wired electromechanical devices. Because of this difference, and also because of the wide variety of uses for solid state equipment, all persons responsible for applying this equipment must satisfy themselves that each intended application of this equipment is acceptable.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.

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### WARNING



Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.

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### IMPORTANT

Identifies information that is critical for successful application and understanding of the product.

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### ATTENTION



Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you identify a hazard, avoid a hazard, and recognize the consequence

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### SHOCK HAZARD



Labels may be on or inside the equipment, for example, a drive or motor, to alert people that dangerous voltage may be present.

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### BURN HAZARD



Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.

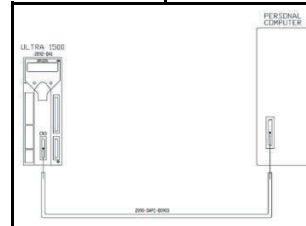
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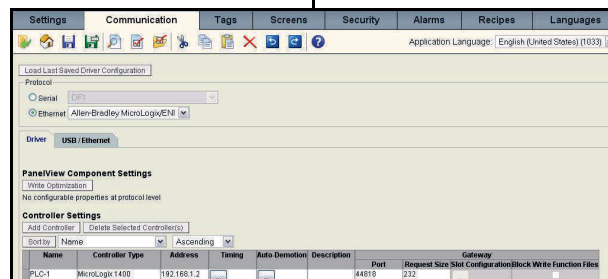
Follow the path below to complete your Simple Motion Control application.

Connected Components  
Building Blocks, publication  
[CC-QS001](#)



[Chapter 1 Ultra1500 Drive Integration](#)

[Chapter 2 System Validation and Application Tips](#)



[Chapter 3 Control Program Integration](#)

Address	Symbol	Scope	Description
\$2461/0	BDCST_CMD_PFCG_USRD	Global	Broadcast: Command Word
\$2461/0	BDCST_CMD_PFCG_DBSL	Global	Broadcast: Disable Command
\$2461/1	BDCST_CMD_PFCG_ENBL	Global	Broadcast: Enable Command
\$2461/2	BDCST_CMD_PFCG_STOP	Global	Broadcast: Stop Command
\$2461/3	BDCST_CMD_PFCG_MOVE	Global	Broadcast: Move Command
\$2461/4	BDCST_CMD_PFCG_JOG	Global	Broadcast: Jog Command
\$2461/5	BDCST_CMD_PFCG_START	Global	Broadcast: Start User Program (Sequence)
\$2461/6	BDCST_CMD_PFCG_CLR_FUT	Global	Broadcast: Clear Fault Command
\$2461/7	BDCST_CMD_PFCG_FWD	Global	Broadcast: Forward Command
\$2461/8	BDCST_CMD_PFCG_REV	Global	Broadcast: Reverse Command
\$2461/9	BDCST_CMD_PFCG_TRP_PFP	Global	Broadcast: Ramp Profile Tripsoidal Command
\$2461/10	BDCST_CMD_PFCG_S_PFP	Global	Broadcast: Ramp Profile S' curve Command
\$2461/11	BDCST_CMD_PFCG_PDTR	Global	Broadcast: Redefine Relative Position Command
\$2461/12	BDCST_CMD_OP_DBSL_ON	Global	Broadcast: Disable Operator Screen Mode (0:Not Disabled, 1:Disabled)
\$2461/1	AXI_CMD_PFCG_USRD	Global	Axis 1: Axis Command Word: From User Program
\$2461/0	AXI_CMD_PFCG_DBSL	Global	Axis 1: Disable Command
\$2461/1	AXI_CMD_PFCG_ENBL	Global	Axis 1: Enable Command
\$2461/2	AXI_CMD_PFCG_STOP	Global	Axis 1: Stop Command
\$2461/3	AXI_CMD_PFCG_MOVE	Global	Axis 1: Move Command
\$2461/4	AXI_CMD_PFCG_JOG	Global	Axis 1: Jog Command
\$2461/5	AXI_CMD_PFCG_START	Global	Axis 1: Start User Program
\$2461/6	AXI_CMD_PFCG_CLR_FUT	Global	Axis 1: Clear Fault Command
\$2461/7	AXI_CMD_PFCG_FWD	Global	Axis 1: Forward Command
\$2461/8	AXI_CMD_PFCG_REV	Global	Axis 1: Reverse Command
\$2461/9	AXI_CMD_PFCG_TRP_PFP	Global	Axis 1: Ramp Profile Tripsoidal Command
\$2461/10	AXI_CMD_PFCG_S_PFP	Global	Axis 1: Ramp Profile S' curve Command
\$2461/11	AXI_CMD_PFCG_PDTR	Global	Axis 1: Redefine Relative Position Command

**Notes:**

	<b>Preface</b>	
	Introduction . . . . .	7
	Conventions Used in This Manual . . . . .	8
	Additional Resources . . . . .	9
	<b>Chapter 1</b>	
<b>Ultra1500 Drive Integration</b>	Introduction . . . . .	11
	Before You Begin . . . . .	11
	What You Need. . . . .	12
	Follow These Steps . . . . .	12
	Connect to the Ultra1500 Drive via Ultraware . . . . .	13
	Reset the Drive to Factory Settings . . . . .	14
	Configure the Drive Operation Mode Parameter . . . . .	15
	Configure the Drive Follower Parameters . . . . .	15
	Configure the Drive Encoder Output Parameters. . . . .	16
	Configure the Drive Digital Input parameters . . . . .	17
	Configure the Drive Digital Output Parameters . . . . .	17
	Save the Drive Parameters . . . . .	18
	Configure Your Application-specific Drive Parameters. . . . .	18
	<b>Chapter 2</b>	
<b>System Validation and Application Tips</b>	Introduction . . . . .	19
	Before You Begin . . . . .	19
	What You Need. . . . .	19
	Follow These Steps . . . . .	20
	Multiple Drive Considerations . . . . .	20
	Configure Controller-to-Drive Communication . . . . .	21
	Configure PVC Terminal-to-Controller Communication. . . . .	23
	Understanding the Network Overview Screen Functionality. . . . .	24
	Test the Simple Motion Control Functionality . . . . .	26
	Navigate the Program Mode Screen . . . . .	26
	Navigate the Operator Mode Screen . . . . .	28
	Test the Operator Mode Functionality . . . . .	30
	Test the Program Mode Functionality . . . . .	32
	<b>Chapter 3</b>	
<b>Control Program Integration</b>	Introduction . . . . .	35
	Before You Begin . . . . .	35
	What You Need. . . . .	36
	Follow These Steps . . . . .	36
	Review the Ladder Logic Structure . . . . .	37
	Review the Modes of Operation. . . . .	38
	Review the Program Mode Commands . . . . .	39
	Customize the Axis User Program Ladder Logic. . . . .	41
	Customize the Machine Control Ladder Logic . . . . .	42
	Alter the Ultra1500 Drive Follower Gear Ratio. . . . .	44

**Notes:**

## Introduction

This quick start is designed to provide a way to implement a connected component for simple motion control.

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**IMPORTANT**

The Simple Motion Control Connected Component Building Block uses predefined configurations in the Ultra1500 drive (such as gear ratio and output ratio) and the MicroLogix 1400 controller (such as pulse train output, high speed counters, and input filters) to create a functional connected component solution. Altering or failing to correctly configure the settings and parameters explained in [Chapter 1](#)...[Chapter 3](#) or failure to use the pre-configured RSLogix 500 files provided with the Simple Motion Control Building Block may result in unexpected behavior and potentially unexpected motion. If you want to alter the Simple Motion Control Connected Component configurations or application code, consult the user manuals for each related product to understand the ramifications of your desired changes.

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**IMPORTANT**

Use this Quick Start in conjunction with the Connected Components Building Blocks Quick Start, publication [CC-QS001](#). Refer to [Additional Resources on page 9](#) for a listing of other related documents.

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To assist in the design and installation of your system, application files and other information are provided on the Connected Component Building Blocks Overview CD, publication CC-QR001. The CD provides bills of materials (BOM), CAD drawings for panel layout and wiring, control programs, Human Machine Interface (HMI) screens, and more. With these tools and the built-in best-practices design, the system designer is free to focus on the design of their machine control and not on design overhead tasks.

The beginning of each chapter contains the following information. Read these sections carefully before beginning work in each chapter:

- **Before You Begin** - This section lists the steps that must be completed and decisions that must be made before starting that chapter. The chapters in this quick start do not have to be completed in the order in which they appear, but this section defines the minimum amount of preparation required before completing the current chapter.
- **What You Need** - This section lists the tools that are required to complete the steps in the current chapter. This includes, but is not limited to, hardware and software.
- **Follow These Steps** - This illustrates the steps in the current chapter and identifies which steps are required to complete the examples.

## Conventions Used in This Manual

This manual uses the following conventions.

Convention	Meaning	Example
Check or uncheck	To activate or deactivate a checkbox.	Check Disable Keying.
Click	Click the left mouse button once while the cursor is positioned on object or selection.	Click Browse.
Double-click	Click the left mouse button twice in quick succession while the cursor is positioned on object or selection.	Double-click the application icon.
Expand	Click the + to the left of a given item / folder to show its contents.	Expand 1768 Bus under I/O Configuration.
Right-click	Click the right mouse button once while the cursor is positioned on object or selection.	Right-click the 1768 Bus icon.
Select	Using the mouse to highlight a specific option.	Select the New Module folder.
Enter	What you type.	Enter your choice.
Press	Pressing a specific key on the keyboard.	Press Enter.
>	Use this symbol to indicate the sub-menu name.	Choose File>Menu>Options.

## Additional Resources

Resource	Description
Connected Components Building Blocks Quick Start, publication <a href="#">CC-QS001</a>	Provides information on how to select products and gain access to panel and wiring information.
Connected Component Building Blocks Overview CD, publication CC-QR001	Provides files for the Connected Component Building Blocks.
MicroLogix 1400 Programmable Controllers User Manual, publication <a href="#">1766-UM001</a>	Provides information on using the MicroLogix 1400 programmable controller.
MicroLogix 1400 Programmable Controllers Installation Instructions, publication <a href="#">1766-IN001</a>	Provides information on using the MicroLogix 1400 programmable controller.
MicroLogix 1400 Programmable Controllers Instruction Set Reference Manual, publication <a href="#">1766-RM001</a>	Provides information on using the MicroLogix 1400 programmable controller RSLogix 500 instruction set.
PanelView Component Operator Terminals User Manual, publication <a href="#">2711C-UM001</a>	Provides information on using the PanelView Component HMI terminals.
Ultra1500 Digital Servo Amplifiers User Manual, publication <a href="#">2092-UM001</a>	Provides information on installing the Ultra1500 drive, including wiring and configuration options.
Ultraware Software User Manual, publication <a href="#">2098-UM001</a>	Provides information on using the Ultraware software including creating, opening and saving Ultraware files as well as changing drive parameters.
<a href="http://www.ab.com">http://www.ab.com</a>	Provides access to the Allen-Bradley website.
<a href="http://www.rockwellautomation.com/knowledgebase">http://www.rockwellautomation.com/knowledgebase</a>	Provides access to self-service support.
<a href="http://www.rockwellautomation.com/components/connected">http://www.rockwellautomation.com/components/connected</a>	Provides access to the Connected Components website.



**Notes:**

# Ultra1500 Drive Integration

## Introduction

In this chapter, you configure the Ultra1500 drive parameters as necessary for the MicroLogix 1400 controller to communicate with the drive. (Configuration is done by using your personal computer connected to the drive.)

The Ultra1500 drive communicates with the MicroLogix 1400 controller by using discrete I/O connections, including Pulse Train Output step/direction signals. Each of your Ultra1500 drives must be configured by using Ultraware software to send/receive the required discrete I/O to/from the MicroLogix 1400 controller. This chapter provides step-by-step instructions for configuring each of your Ultra1500 drives, whether you are using the 1-axis, 2-axis, or 3-axis Simple Motion Control Building Block solution.

In addition, this chapter specifies the minimum number of parameters that need to be changed from the factory default settings in order to establish communication with the MicroLogix 1400 controller. For your machine application, there may be other drive parameters that need to be adjusted as well. You will need to consult the drive documentation for information on all other drive parameters.

## Before You Begin

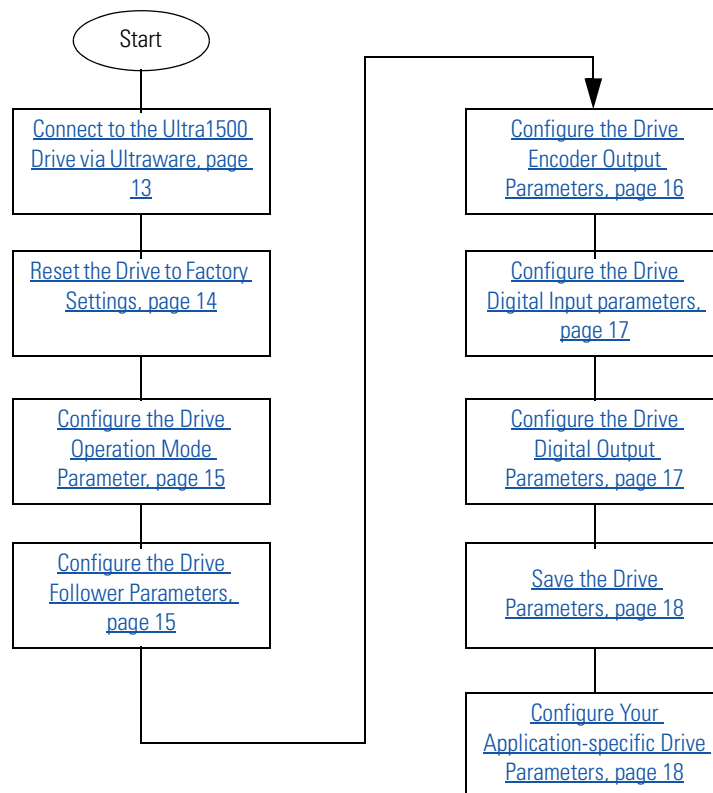
- Review the Connected Components Building Blocks Quick Start, publication CC-QS001.
- Install Ultraware software.
- Apply power to your drive.

## What You Need

- Personal computer with serial connection
- Ultra1500 drives
- Ultra1500 serial interface cable
- Ultraware software
- MicroLogix 1400 controller
- Connected Components Building Blocks Overview CD, publication CC-QR001

## Follow These Steps

Follow these steps to configure **each** of your Ultra1500 drives.



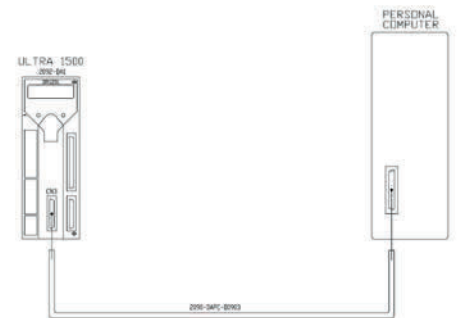
## Connect to the Ultra1500 Drive via Ultraware

Ultra1500 drives are configured by using Ultraware (catalog number 2098-UWCPRG) software. Ultraware software is a Windows-based application that allows drive configuration to be done offline and saved to disk. By using the Ultraware software, your personal computer can be connected to the Ultra1500 drives with the Ultra1500 serial interface cable (catalog number 2090-DAPC-D09xx).

To configure the Operation mode parameter, perform the following steps.

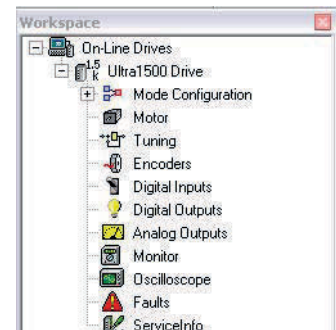
1. Connect your personal computer's serial connection to the Ultra1500 drive's CN3 connection by using the Ultra1500 serial interface cable.

Consult the Ultra1500 drive user manual for further information.



2. Go online with the Ultra1500 drive by using the Ultraware software.

Consult the Ultra1500 drive user manual for further information.



### TIP

Your Ultra1500 drive must be listed in the On-Line Drives section, as shown above. If it is not listed in the On-Line Drives section, then your Ultra1500 drive is still offline.

After your Ultra1500 drive is online and you are able to browse its parameters, continue to the next section.

以上内容仅为本文档的试下载部分，为可阅读页数的一半内容。如要下载或阅读全文，请访问：<https://d.book118.com/746154130005010212>